

Using ANFIS as Indicator in the Networks Containing SVC and STATCOM for Voltage Collapse Phenomena

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Abstract : This paper focuses on using an ANFIS indicator for its proximity to collapse point with emphasizing on application of two Flexible AC Transmission System (FACTS) devices' namely, Static Var Compensator (SVC) and Static Compensator (STATCOM), In order to study the effects on voltage collapse phenomena in power systems. Based on system results at the point of collapse 'Application of these devices loadability or increase could increase loadability margin to collapse point. Also, ANFIS as an indicator for proximity to collapse point has been applied successfully. The IEEE 14 bus test system is used to illustrate the effects of FACTS devices on voltage collapse phenomena and applying of ANFIS as an indicator for proximity index simulations.

Keywords: ANFIS, SVC, STATCOM, Voltage Collapse, Loadability Margin.

استفاده از ANFIS به عنوان نشانگری برای پدیده فرو افتادن ولتاژ در شبکه‌های دارای ادوات FACTS

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چکیده: این مقاله بر روی استفاده از نشانگر ANFIS برای تعیین نزدیکی به نقطه فروافتادن ولتاژ در سیستم‌های قدرتی که ادوات FACTS به خصوص SVC, STATCOM وجود دارند متمرکز است تا اثرات این وسایل را بر روی پدیده فروافتادن در سیستم‌های قدرت مورد مطالعه قرار دهد. همچنین استفاده از ANFIS به عنوان نشانگری برای تعیین نزدیکی به نقطه مرز افتادن بطور موفقیت آمیزی استفاده شده است. سیستم آزمون ۱۴ شینه IEEE برای نمایش اثر ادوات FACTS بر روی پدیده فروافتادن ولتاژ و بکارگیری ANFIS به عنوان نشانگری برای نزدیکی به نقطه فروافتادن مورد شبیه سازی قرار گرفته است.

کلمات کلیدی: حاشیه بارگذاری سیستم، فاصله تا نقطه فرو افتادن ولتاژ، فرو افتادن ولتاژ، ANFIS، SVC، STATCOM.

1. Introduction

Voltage collapse problems in power systems have been a permanent concern for the electric utilities, as several major black outs through out the world have been directly associated to this phenomena, e.g. WSCC July 1996 and etc. Many analysis methods have been proposed and currently used for the study of this problem [1,2,3]. Most of these techniques are based on the identification of system equilibria where the corresponding jacobians become singular. These equilibrium points are typically referred to point of voltage collapse and can be mathematically associated to saddle-node bifurcation [4,5].

The voltage collapse point are also known as maximum loadability point. In fact, the voltage collapse problem can be restated as an optimization problem where the objective function is to maximize certain system parameters typically associated to load levels [6,7,8,9]. Hence, voltage collapse techniques may also be used to compute the maximum power that can be transmitted through the transmission system. In the new competitive energy market literature also known as total transfer capability or as available transfer capability(ATC) [10].

It is well known that shunt and series compensation can be used to increase the maximum transfer capabilities of power networks [11]. With the improvements in current and voltage handling capabilities of power electronic devices that have allowed for development of flexible ac transmission system devices. The possibility has arisen to using different types of controllers for efficient shunt and series compensation. Thus, FACTS devices based on shunt connection on the network such as static var compensators (SVC) and static compensator (STATCOM) are being used by several electric utilities to compensate their systems [12]. Recently, various types of devices for shunt and series compensation based on voltage source convertors (VSC) namely, SSSC, UPFC, have been proposed and implemented [13]. This paper concentrate on studying the effects of SVC and STATCOM on voltage collapse phenomena using continuation power flow (CPF) method [14,15].

Adaptive Neuro Fuzzy Inference System (ANFIS) as an intelligent system uses of two

major feature of Neural networks learning capability and also, fuzzy logic inference capability. So, ANFIS is very suitable for challenging situations where complex mathematical expression and involving uncertainty with inferences. In large scale power system calculating loadability margin is complicated problem. So, learning of conceptual mathematical model based on learning phenomena at neural networks adequately suitable in proximity prediction to voltage collapse point and also, fuzzy inference feature suitable for uncertainty contained in operating point.

Section 2 briefly introduces the basic mathematical tools required for the analysis of voltage collapse phenomena. In section 3 a detailed description of SVC and STATCOM models are given. Section 3b introduce the ANFIS structure. Section 4 is depicted to simulation of voltage collapse phenomena on IEEE 14 bus test system with implementing SVC and STATCOM and applying ANFIS. Finally, section 5 summarizes the main points of this paper and discusses future research directions.

2. Voltage collapse

Voltage collapse studies and their related tools are typically based on the following general mathematical descriptions of the system :

$$\begin{aligned} \dot{x} &= f(x, y, \lambda, p) \\ 0 &= g(x, y, \lambda, p) \end{aligned} \quad (1)$$

Where $x \in \mathcal{X}^n$ represents the system state variables, corresponding to dynamical states of generators, loads, and any other time varying element in the system such as FACTS devices; $y \in \mathcal{Y}^m$ corresponds to the algebraic variables, usually associated to the transmission system and steady state element models, such as some generators and loads in the network ; $\lambda \in \mathcal{L}^l$ stands for a set of uncontrolled parameters that drive the system to voltage collapse, which are typically used to represent system demand. Vector $p \in \mathcal{P}^k$ is used here to represent system parameters that are directly controllable, such as shunt and series compensation levels.

Based on equation (1) the voltage collapse

point may be defined, under certain assumptions, as the equilibrium point where the related system jacobian is singular, i.e. the point $(x_0, y_0, \lambda_0, p_0)$ where

$$\begin{bmatrix} f(x, y, \lambda, p) \\ g(x, y, \lambda, p) \end{bmatrix} = F(z, \lambda, p) = 0 \quad (2)$$

and $D_x F|_0$ has a zero eigenvalue[15]. This equilibrium is typically associated to a saddle-node bifurcation point.

For a given set of controllable parameters P_0 , voltage collapse studies usually concentrate on determining the collapse or bifurcation point (x_0, y_0, λ_0) , where λ_0 typically corresponds to the maximum loading level or loadability margin in P.U., %, MW or MVA depending on how the load variation are defined. Based on bifurcation theory, two basic tools have been defined and applied to computation of this collapse point, namely, direct and continuation methods [16].

In voltage collapse studies, the continuation method shows many advantages, so, most of the researchers apply this technique to trace voltage profile at various buses of the test power system, with respect to changes of loading level λ , namely, Continuation Power Flow (CPF).

In this paper the continuation power flow algorithm with smooth changes of loading level at various buses of the system, is chosen for simulation purpose.

3. SVC and STATCOM models and Introducing ANFIS

A-1) SVC

Basic model for SVC built around Thyristor controlled reactor (TCR). Therefore the FC-TCR structure depicted in fig. 1, is used in this paper. The TCR consist of a fixed reactor of inductance L and a bi-directional thyristor valve. The thyristor valves are fired symmetrically in an angle α control range from 90^0 to 180^0 , with respect to the capacitor voltage. The valves automatically turn off approximately at current zero crossing.

The steady state V-I characteristics for this type controller are depicted in fig. 2, and corresponds to the well-known control characteristics of a typical SVC. A SVC steady state model can be shown with the equations representing these steady state characteristics; thus, the power flow equations of the SVC in this case are

$$\begin{bmatrix} V_k - V_{ref} - X_{SL} \cdot I \\ g_1(\alpha, V, V_k, I, Q, B_e) \end{bmatrix} = 0 \quad (3)$$

$$g_1(\alpha, V, V_k, I, Q, B_e) = \left[B_e - \frac{2\alpha - \sin 2\alpha - \pi(2 - X_L/X_C)}{\pi X_L} \right] I + V_i B_e \quad (4)$$

$$Q + V_i^2 B_e$$

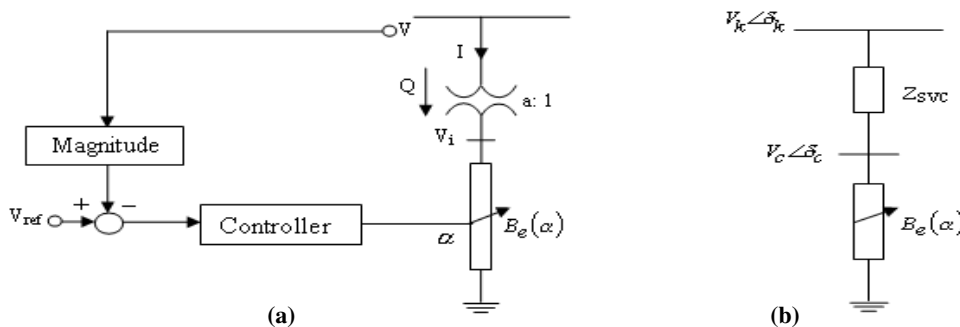


Fig. 1. (a) basic construction of SVC (b) simplified electric model

which can be directly included in any power flow program.

For the steady state model to be complete, all SVC controll limits should be adequately represented.

A-2) STATCOM

The STATCOM is assumed to be connected at buse K as illustrated in fig. 3. The STATCOM model is not loss less, i.e. , the active power P at node K absorbed by internal componenets of STATCOM. Thus, the STATCOM can be represented by the following set of equations, which include control system equations and assuming sinusoidal current in the STATCOM [18,19]. where most variables are defined on figure 3.

$$\begin{bmatrix} V_k - V_{ref} - Z_{sh} \cdot I \\ g_1(V_{sh}, V_k, I_{sh}, Q, P) \end{bmatrix} = 0 \tag{5}$$

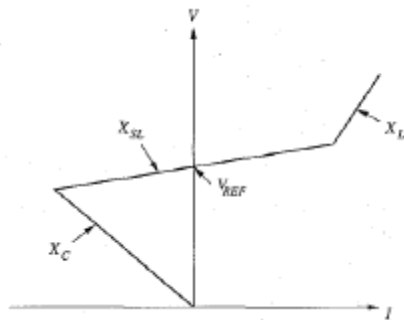


Fig. 2. SVC steady state characteristic

$$g_1(V_{sh}, V_k, I_{sh}, Q, P) = \begin{bmatrix} P_k - G_{sh} V_k^2 + V_k V_{sh} Y_{sh} \cos(\delta_k - \delta_{sh} - \theta_{sh}) \\ Q_k - V_k^2 B_{sh} + V_k V_{sh} Y_{sh} \sin(\delta_k - \delta_{sh} - \theta_{sh}) \\ \sqrt{P_k^2 + Q_k^2} = I_{sh} \cdot V_k \end{bmatrix} = 0 \tag{6}$$

A steady state model for this STATCOM controller can be presented with equations on (5) wich Containing steady state control Characteristics. STATCOM can only preform reactive power and does not inject real power to system. But due to lossey components of the STATCOM it absorbes real power from the connected bus K [18,19].

B) Introducing ANFIS

Adaptive Neuro Fuzzy Inference System (ANFIS) is a network that's be able to adapet itself with learning process. ANFIS performance is like to Fuzzy inference systems and it works based on rules that have been learned at learning process. If we assume a fuzzy system with two inputs x,y and one output z , it can be represented with the fuzzy rules as below.

Rule 1 :
 if x is A₁ and y is B₁ then f₁ = p₁x + q₁y + r₁ (7)
 Rule 2 :
 if x is A₂ and y is B₂ then f₂ = p₂x + q₂y + r₂

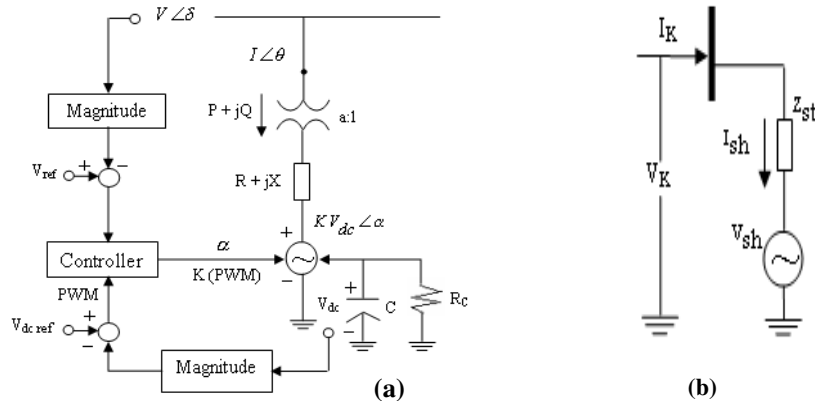


Fig. 3. (a)STATCOM bus voltage control (b) simplified electric model

Also, if using centres averaging defuzzification method the outputs can be defined [20].

$$f = \frac{w_1 f_1 + w_2 f_2}{w_1 + w_2} = \frac{\bar{w}_1 f_1 + \bar{w}_2 f_2}{st} \tag{8}$$

$$\bar{w}_1 = \frac{w_1}{w_1 + w_2}, \quad \bar{w}_2 = \frac{w_2}{w_1 + w_2}$$

The ANFIS network structure that's equivalent to the above system (Eq. 7 & Eq. 8) shown at the Fig. 4.

Briefly introducing the ANFIS structure layers so, layer one transforms the crisp inputs to fuzzy quantities by passing through membership functions that often chosen bell type functions. Layer two implements a product operation on the outputs of previous layer. Layer three normalize the outputs of the layer two. The fourth layer applies product operation on the previous layer output and inputs to the network. Finally, layer five adds the outputs the fourth layer and

performs the ANFIS network outputs that is similar to Sugeno type fuzzy systems [21].

Learning process for the ANFIS networks can be done as same as neural networks based on Gradient Descent, Levenberg-Marquard and Hybrid methods. Performance criteria for learning process is Least Mean Square Error and in the simulations of this paper online backpropagation error have been used [22].

4. Simulation

An IEEE 14 bus test system was used to try models and ANFIS network discussed in this paper. The generators are modeled as standard PV buses with both P and Q limits; loads are represented as constant PQ loads. The P and Q load powers are not voltage dependent and are assumed to change as follows :

$$P_L = P_{L0}(1 + \lambda) \tag{9}$$

$$Q_L = Q_{L0}(1 + \lambda)$$

Where P_{L0} and Q_{L0} represents the base case loading condition.

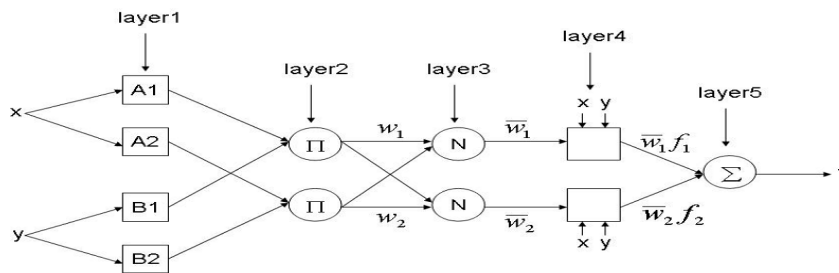


Fig. 4. ANFIS network structure

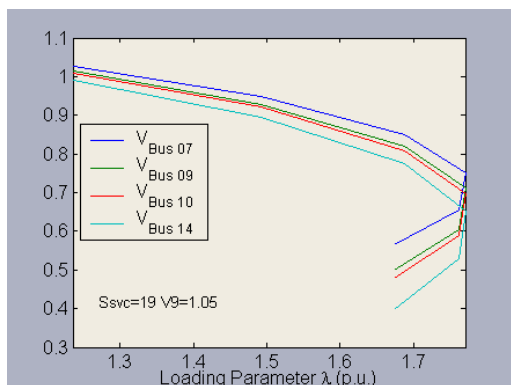


Fig. 5. base case continuation power flow

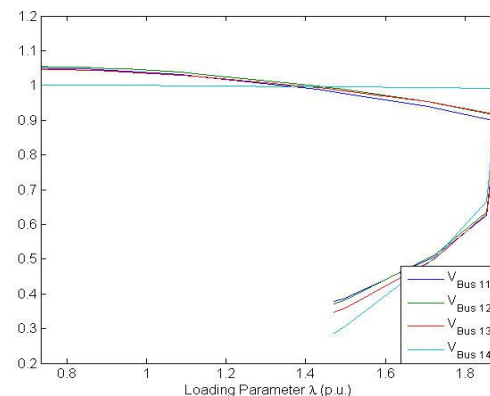


Fig. 6. SVC placement at bus 14

Fig. 5 depicts the voltage profiles of four buses identified as “critical” namely, bus No. 14. The system presents a collapse or maximum loading point, where the system Jacobian matrix become singular at $\lambda_0=1.7063$ p.u. Based on largest entries in the right and left eigenvectors associated to the zero eigenvalue at the collapse point, bus 14 is indicated as the “critical voltage bus” needing Q support.

A) SVC

Based on collapse analysis bus 14 is targeted as the first location for an SVC. The results of locating the SVC at the desired bus are depicted in the voltage profile of fig. 6. The new maximum loading level in this condition is $\lambda_0 = 1.882$ p.u.

B) STATCOM

The second type FACTS controller i.e. STATCOM is implemented on test system. A similar approach to the one followed to analyze the SVC effect on maximum loadability is used to study the corresponding effects of a STATCOM. Fig. 7 illustrates the effects of the STATCOM on maximum loading level, when located at critical bus.

C) ANFIS Implementation

For being able to face with operation problems on large scale power systems, on line indicators to situation awareness is necessary. The ANFIS capability of learning observed data involving uncertainty and then making inference for unobserved data make it suitable for application

such as this. Because at the critical situations time consuming methods as continuation power flow could not perform really. But having a before learned ANFIS network and with feeding the present situation available data of the power system, it can perform the loading parameter as soon as possible (on line). So, operational aspect of an on line indicator or situation awareness tool for power system loading is critical.

The ANFIS structure used here for the above purpose is shown at the Fig. 8. For each input three Gaussian membership function is adopted. The inputs to the ANFIS network are bus voltages of the IEEE 14 bus test system that obtained from continuation power flow explained at previous section.

Learning process have been done successfully and Fig. 9 shows the result. Only with three rules the resultant ANFIS network be able to work perfectly. So, it has a very simple rule base and then, responses on line.

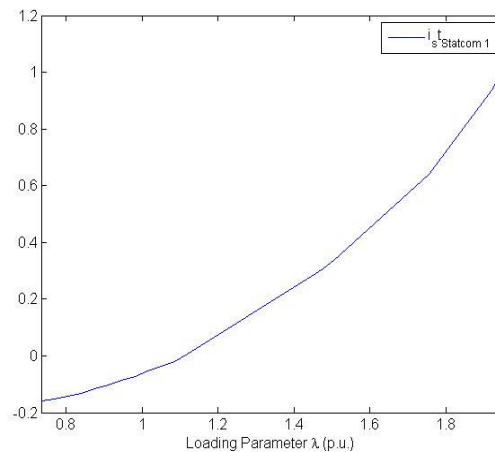


Fig. 7. ISTATCOM placement at bus 14

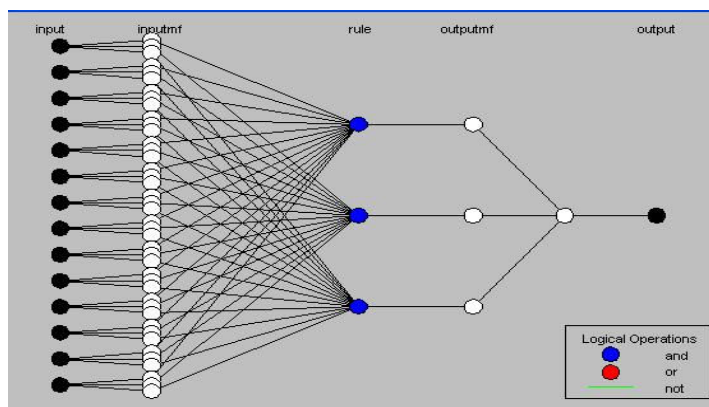


Fig. 8. ANFIS structure used for base case IEEE 14 bus system

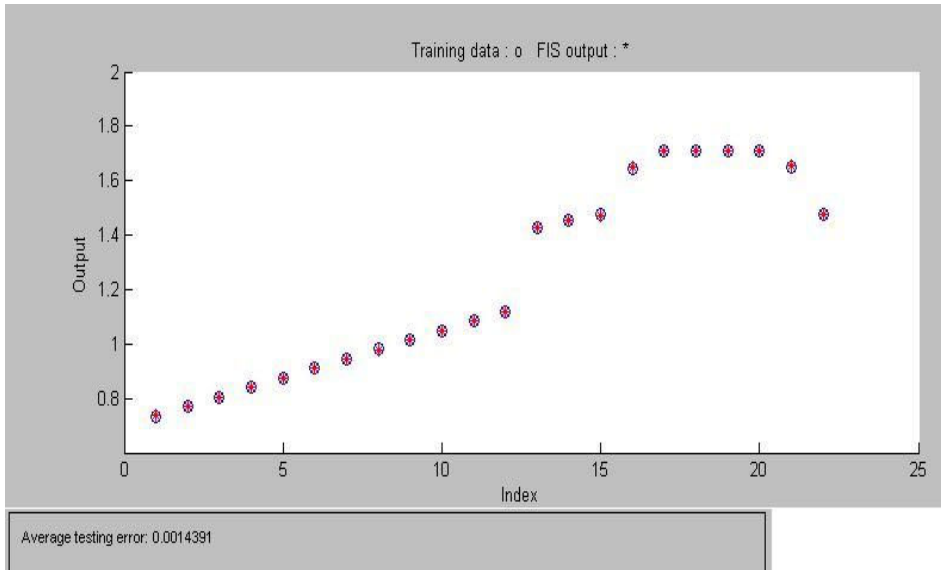


Fig. 8. ANFIS learned data and its output for base case IEEE 14 bus system

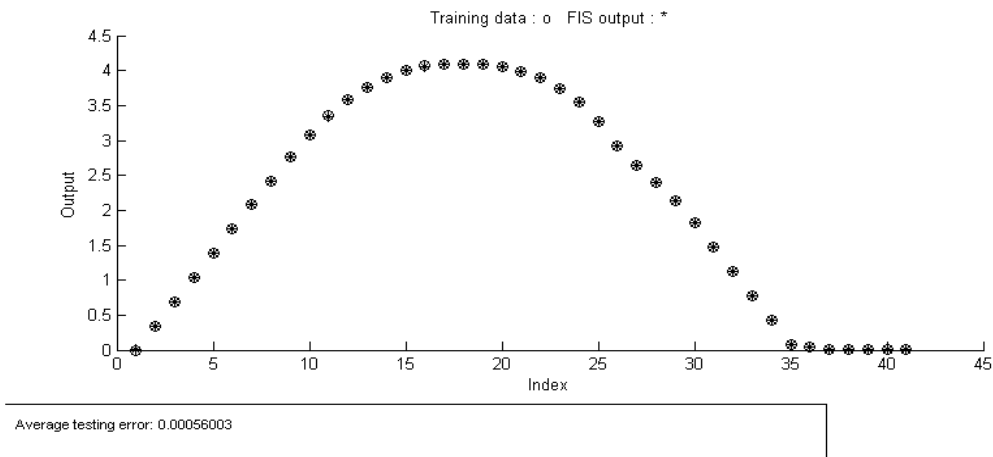


Fig. 9. ANFIS learned data and its output for case inserting SVC at IEEE 14 bus system

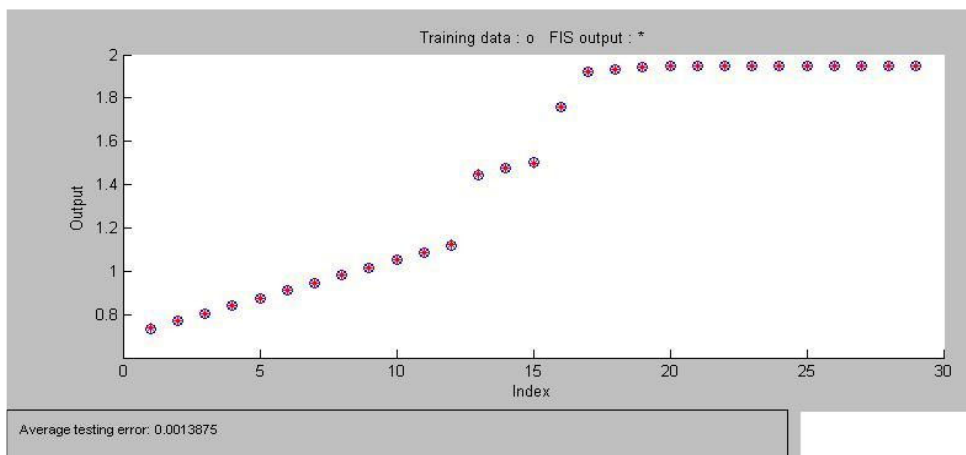


Fig. 10. ANFIS learned data and its output for case inserting STATCOM at IEEE 14 bus system

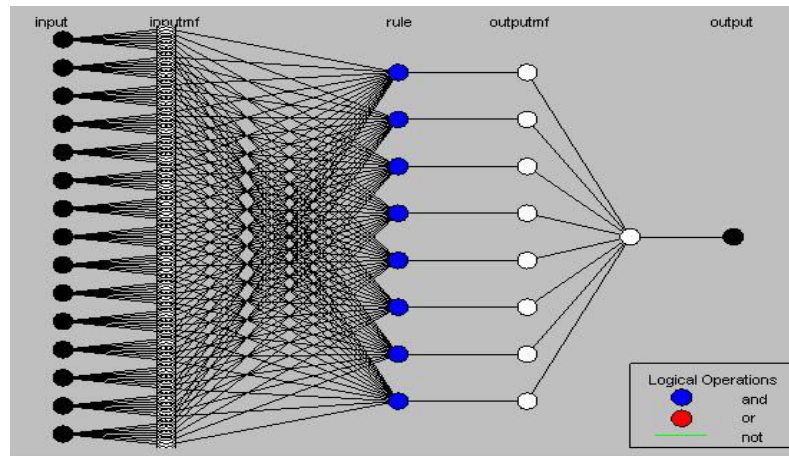


Fig. 11. ANFIS structure used for IEEE 14 bus system including SVC(STATCOM)

The above procedure repeated for IEEE 14 bus test system with insertin SVC and STATCOM . Result of the ANFIS Network is shown at the Fig. 9 and Fig.10 respectively. Also the structure of the new ANFIS network that includes SVC(STATCOM) added input data is shown at Fig.11. The added input contains suseptance of SVC for Trying with SVC and STATCOM current for doing with STATCOM.

5. Conclusion

The results presented in this paper clearly shows how SVC and STATCOM can be used to increase system loadability in practical power systems. Based on simulation results obtained in the paper can conclude that, both SVC and STATCOM can increase system loadability or margin to voltage collapse.

Also , using of ANFIS network for power system as an indicator for loading paparameter estimation introduced. The simulation results indicate that applying ANFIS network in large scale power system for situation awareness or loading condition monitoring produces efficient and reliable response. ANFIS on line output performing make it suitable for critical operational conditions such as stall to prone networks.

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